

ANTREX Electronics

Electronic Components Sourcing Information

Product Reference Information

Part Number:	TLV5619CDWR
Manufacturer:	Texas Instruments
Package:	20-SOIC (0.295", 7.50mm Width)
Availability:	Please confirm with sales

Product Page:

<https://antrexco.com/product/details/texas-instruments/tlv5619cdwr.html>

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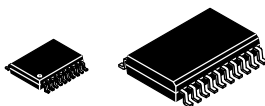
CoC / RoHS / REACH documents available on request

Secure sourcing support for OEM / EMS projects

Note:

This PDF includes an ANTREX product reference cover page.

The original manufacturer datasheet follows from the next page.



2.7 V TO 5.5 V 12-BIT PARALLEL DIGITAL-TO-ANALOG CONVERTER WITH POWER DOWN

FEATURES

- Single Supply 2.7-V to 5.5-V Operation
- ± 0.4 LSB Differential Nonlinearity (DNL),
 ± 1.5 LSB Integral Nonlinearity (INL)
- 12-Bit Parallel Interface
- Compatible With TMS320 DSP
- Internal Power On Reset
- Settling Time 1 μ s Typ
- Low Power Consumption:
 - 8 mW for 5-V Supply
 - 4.3 mW for 3-V Supply
- Reference Input Buffers
- Voltage Output
- Monotonic Over Temperature
- Asynchronous Update

APPLICATIONS

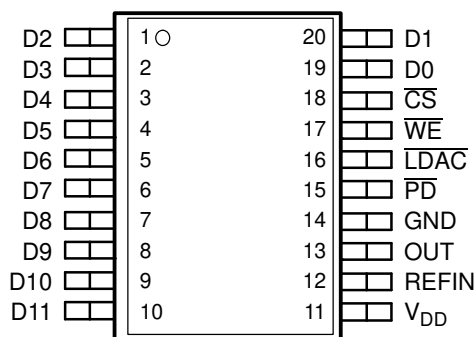
- Battery Powered Test Instruments
- Digital Offset and Gain Adjustment
- Battery Operated/Remote Industrial Controls
- Machine and Motion Control Devices
- Cordless and Wireless Telephones
- Speech Synthesis
- Communication Modulators
- Arbitrary Waveform Generation

DESCRIPTION

The TLV5619 is a 12-bit voltage output DAC with a microprocessor and TMS320 compatible parallel interface. The 12 data bits are double buffered so that the output can be updated asynchronously using the $\overline{\text{LDAC}}$ pin. During normal operation, the device dissipates 8 mW at a 5-V supply and 4.3 mW at a 3-V supply. The power consumption can be lowered to 50 nW by setting the DAC to power-down mode.

The output voltage is buffered by a $\times 2$ gain rail-to-rail amplifier, which features a Class A output stage to improve stability and reduce settling time.

**DW OR PW PACKAGE
(TOP VIEW)**



AVAILABLE OPTIONS

PACKAGE		
T_A	SMALL OUTLINE (DW)	TSSOP (PW)
0°C to 70°C	TLV5619CDW	TLV5619CPW
40°C to 85°C	TLV5619IDW	TLV5619IPW
40°C to 125°C	TLV5619QDW	—

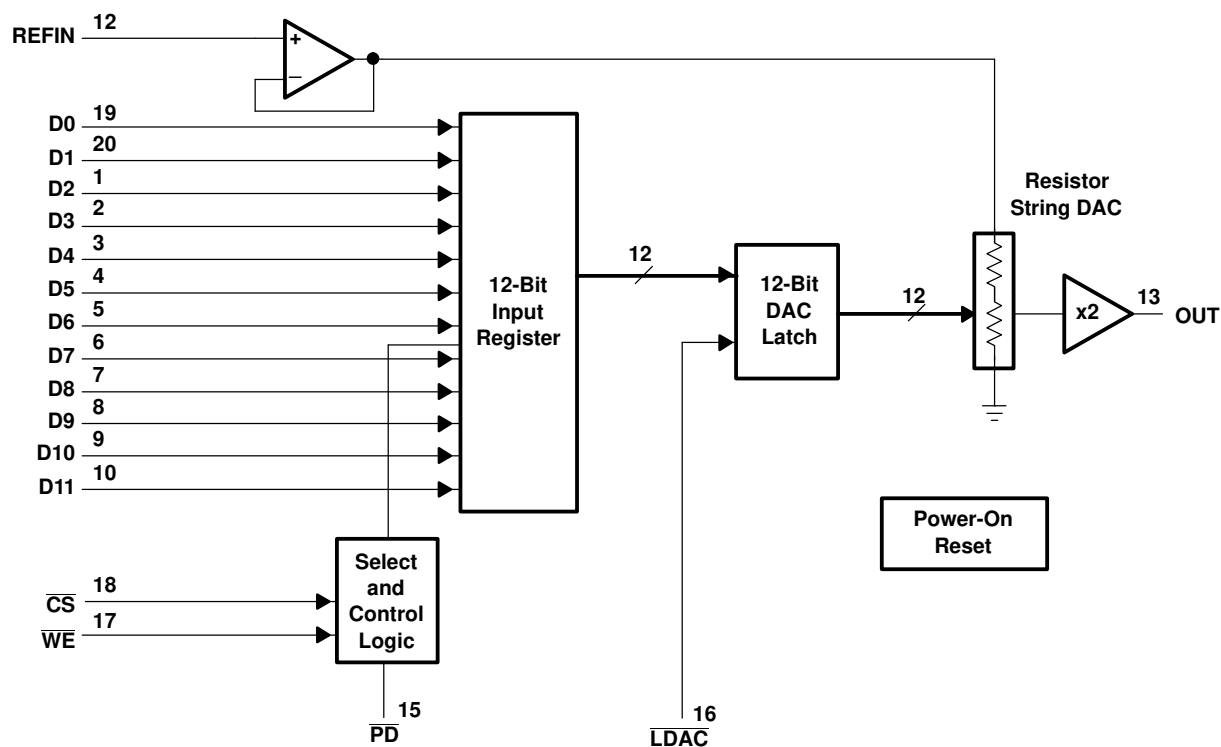


Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

FUNCTIONAL BLOCK DIAGRAM



Terminal Functions

NAME	TERMINAL NO.	I/O	DESCRIPTION
$\overline{CS}$	18	I	Chip select
D0 (LSB)-D11 (MSB)	19, 20, 1-10	I	Parallel data input
GND	14		Ground
$\overline{LDAC}$	16	I	Load DAC
OUT	13	O	Analog output
$\overline{PD}$	15	I	When low, disables all buffer amplifier voltages to reduce supply current
REFIN	12	I	Voltage reference input
V_{DD}	11		Positive power supply
$\overline{WE}$	17	I	Write enable

ABSOLUTE MAXIMUM RATINGS

over operating free-air temperature range (unless otherwise noted)⁽¹⁾

		UNIT
Supply voltage (V_{DD} to GND)		7 V
Analog input voltage range		- 0.3 V to $V_{DD} + 0.3$ V
Reference input voltage		$V_{DD} + 0.3$ V
Digital input voltage range to GND		- 0.3 V to $V_{DD} + 0.3$ V
Operating free-air temperature range, T_A	TLV5619C	0°C to 70°C
	TLV5619I	-40°C to 85°C
	TLV5619Q	-40°C to 125°C
Storage temperature range, T_{stg}		-65°C to 150°C
Lead temperature 1,6 mm (1/16 inch) from case for 10 seconds		260°C

(1) Stresses beyond those listed under „absolute maximum ratings” may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under „recommended operating conditions” is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

RECOMMENDED OPERATING CONDITIONS

				MIN	NOM	MAX	UNIT
Supply voltage, V _{DD} (5-V Supply)				4.5	5	5.5	V
Supply voltage, V _{DD} (3-V Supply)				2.7	3	3.3	V
High-level digital input voltage, V _{IH}	DV _{DD} = 2.7 V			2			V
	DV _{DD} = 5.5 V			2.4			
Low-level digital input voltage, V _{IL}	DV _{DD} = 2.7 V			0.6			V
	DV _{DD} = 5.5 V	TLV5619C and TLV5619I		1			
			TLV5619Q		0.8		
Reference voltage, V _{ref} to REFIN terminal (5-V Supply)				0	2.048	V _{DD} -1.5	V
Reference voltage, V _{ref} to REFIN terminal (3-V Supply)				0	1.024	V _{DD} -1.5	V
Load resistance, R _L				2	10		kΩ
Load capacitance, C _L				100			pF
Operating free-air temperature, T _A	TLV5619C			0	70		°C
	TLV5619I			40	85		
	TLV5619Q			40	125		

ELECTRICAL CHARACTERISTICS

over recommended operating free-air temperature range, supply voltages, and reference voltages (unless otherwise noted)

STATIC DAC SPECIFICATIONS							
PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
Resolution		V _{ref(REFIN)} = 2.048 V at 5 V, 1.024 V at 3 V		12			bits
Integral nonlinearity (INL)		V _{ref(REFIN)} = 2.048 V at 5 V, 1.024 V at 3 V,	See (1)		±1.5	±4	LSB
Differential nonlinearity (DNL)		V _{ref(REFIN)} = 2.048 V at 5 V, 1.024 V at 3 V,	See (2)		±0.4	±1	LSB
E _{ZS}	Zero-scale error (offset error at zero scale)	V _{ref(REFIN)} = 2.048 V at 5 V, 1.024 V at 3 V,	See (3)		±3	±20	mV
Zero-scale-error temperature coefficient		V _{ref(REFIN)} = 2.048 V at 5 V, 1.024 V at 3 V,	See (4)		3		ppm/°C
E _G	Gain error	V _{ref(REFIN)} = 2.048 V at 5 V, 1.024 V at 3 V,	See (5)		±0.25	±0.5	% of FS voltage
Gain error temperature coefficient		V _{ref(REFIN)} = 2.048 V at 5 V, 1.024 V at 3 V,	See (6)		1		ppm/°C
PSRR	Power-supply rejection ratio	Zero scale	See (7) and (8)		65		dB
		Gain			65		

- (1) The relative accuracy or integral nonlinearity (INL), sometimes referred to as linearity error, is the maximum deviation of the output from the line between zero and full scale excluding the effects of zero code and full-scale errors.
- (2) The differential nonlinearity (DNL), sometimes referred to as differential error, is the difference between the measured and ideal 1 LSB amplitude change of any two adjacent codes. Monotonic means the output voltage changes in the same direction (or remains constant) as a change in the digital input code.
- (3) Zero-scale error is the deviation from zero voltage output when the digital input code is zero.
- (4) Zero-scale-error temperature coefficient is given by: $E_{\text{ZS}} \text{ TC} = [E_{\text{ZS}}(T_{\text{max}}) - E_{\text{ZS}}(T_{\text{min}})]/V_{\text{ref}} \times 10^6/(T_{\text{max}} - T_{\text{min}})$.
- (5) Gain error is the deviation from the ideal output ($2 \times V_{\text{ref}} - 1 \text{ LSB}$) with an output load of 10 kΩ excluding the effects of the zero-error.
- (6) Gain temperature coefficient is given by: $E_{\text{G}} \text{ TC} = [E_{\text{G}}(T_{\text{max}}) - E_{\text{G}}(T_{\text{min}})]/V_{\text{ref}} \times 10^6/(T_{\text{max}} - T_{\text{min}})$.
- (7) Zero-scale-error rejection ratio (EZR-RR) is measured by varying the V_{DD} from 4.5 V to 5.5 V dc and measuring the proportion of this signal imposed on the zero-code output voltage.
- (8) Gain-error rejection ratio (EG-RR) is measured by varying the V_{DD} from 4.5 V to 5.5 V dc and measuring the proportion of this signal imposed on the full-scale output voltage after subtracting the zero scale change.

OUTPUT SPECIFICATIONS							
PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
V _O	Voltage output range	R _L = 10 kΩ		0		V _{DD} -0.4	V
Output load regulation accuracy		V _{O(OUT)} = 4.096 V, 2.048 V	R _L = 2 kΩ		0.1	0.29	% of FS voltage
I _{OSC(source)}	Output short circuit source current	V _{O(OUT)} = 0 V, Full scale code	5-V Supply		100		mA
			3-V Supply		25		
I _{O(source)}	Output source current	R _L = 100Ω	5-V Supply		10		mA
			3-V Supply		10		

REFERENCE INPUT (REFIN)					
PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V _{ref} Reference input voltage	See ⁽¹⁾	0		V _{DD} -1.5	V
R _i Reference input resistance			10		MΩ
C _i Reference input capacitance			5		pF
Reference feed through	REFIN = 1 V _{pp} at 1 kHz + 1.024 V dc (see ⁽²⁾)		60		dB
Reference input bandwidth	REFIN = 0.2 V _{pp} + 1.024 V dc at -3 dB		1.4		MHz
DIGITAL INPUTS (D0-D11, $\overline{\text{CS}}$, $\overline{\text{WE}}$, $\overline{\text{LDAC}}$, $\overline{\text{PD}}$)					
I _{IH} High-level digital input current	V _I = V _{DD}			1	μA
I _{IL} Low-level digital input current	V _I = 0 V			1	μA
C _i Input capacitance			8		pF

(1) Reference input voltages greater than V_{DD}/2 will cause output saturation for large DAC codes.

(2) Reference feedthrough is measured at the DAC output with an input code = 0x000 and a V_{ref(REFIN)} input = 1.024 V dc + 1 V_{pp} at 1 kHz.

POWER SUPPLY							
PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
I _{DD}	Power supply current	No load, All inputs 0 V or V _{DD}	5-V Supply	1.6	3	mA	
			3-V Supply	1.44	2.7		
	Power down supply current			0.01	10	μA	

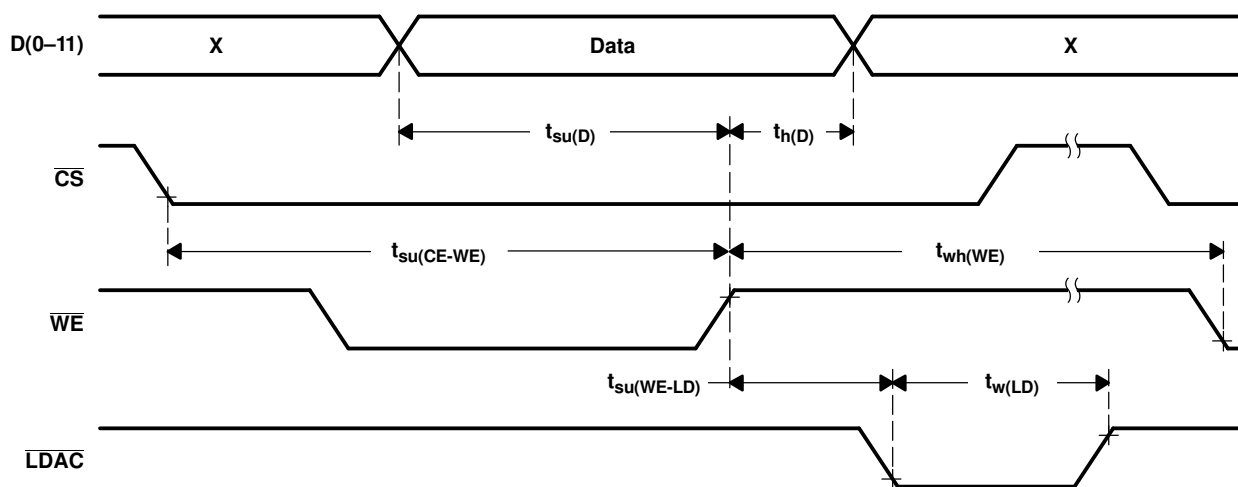
ANALOG OUTPUT DYNAMIC PERFORMANCE					
PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
SR Slew rate	C _L = 100 pF, R _L = 10 kΩ V _{ref(REFIN)} = 2.048 V, V _{ref(REFIN)} = 1.024 V, V _O from 10% to 90% V _O from 90% to 10%	5-V Supply	8	12	V/μs
		3-V Supply	6	9	V/μs
t _s Output settling time (full scale)	To ±0.5 LSB, R _L = 10 kΩ, C _L = 100 pF, See ⁽¹⁾		1	3	μs
Glitch energy	DIN = all 0s to all 1s		5		nV-s
S/N Signal to noise	f _s = 480 kSPS, BW = 20 kHz, C _L = 100 pF, f _{OUT} = 1 kHz, R _L = 10 kΩ, T _A = 25°C, See ⁽²⁾	5-V Supply	65	78	dB
S/(N+D) Signal to noise + distortion	f _s = 480 kSPS, BW = 20 kHz, C _L = 100 pF, f _{OUT} = 1 kHz, R _L = 10 kΩ, T _A = 25°C, See ⁽²⁾	5-V Supply	58	67	
		3-V Supply	58	69	
Total harmonic distortion	f _s = 480 kSPS, BW = 20 kHz, C _L = 100 pF, f _{OUT} = 1 kHz, R _L = 10 kΩ, T _A = 25°C, See ⁽²⁾		68	60	
Spurious free dynamic range	f _s = 480 kSPS, BW = 20 kHz, C _L = 100 pF, f _{OUT} = 1 kHz, R _L = 10 kΩ, T _A = 25°C, See ⁽²⁾		60	72	

(1) Settling time is the time for the output signal to remain within ±0.5 LSB of the final measured value for a digital input code change of 32 to 4063 or 4063 to 32. Limits are ensured by design and characterization, but are not production tested.

(2) 1 kHz sinewave generated by DAC, reference voltage = 1.024 V at 3 V and 2.048 V at 5 V.

TIMING REQUIREMENTS

DIGITAL INPUTS					
		MIN	NOM	MAX	UNIT
t _{su(CS-WE)}	Setup time, $\overline{\text{CS}}$ low before positive $\overline{\text{WE}}$ edge	13			ns
t _{su(D)}	Setup time, data ready before positive $\overline{\text{WE}}$ edge	9			ns
t _{h(D)}	Hold time, data held after positive $\overline{\text{WE}}$ edge	0			ns
t _{su(WE-LD)}	Setup time, positive $\overline{\text{WE}}$ edge before $\overline{\text{LDAC}}$ low	0			ns
t _{wh(WE)}	Pulse width, $\overline{\text{WE}}$ high	25			ns
t _{w(LD)}	Pulse width, $\overline{\text{LDAC}}$ low	25			ns

PARAMETER MEASUREMENT INFORMATION**Figure 1. Timing Diagram**

TYPICAL CHARACTERISTICS

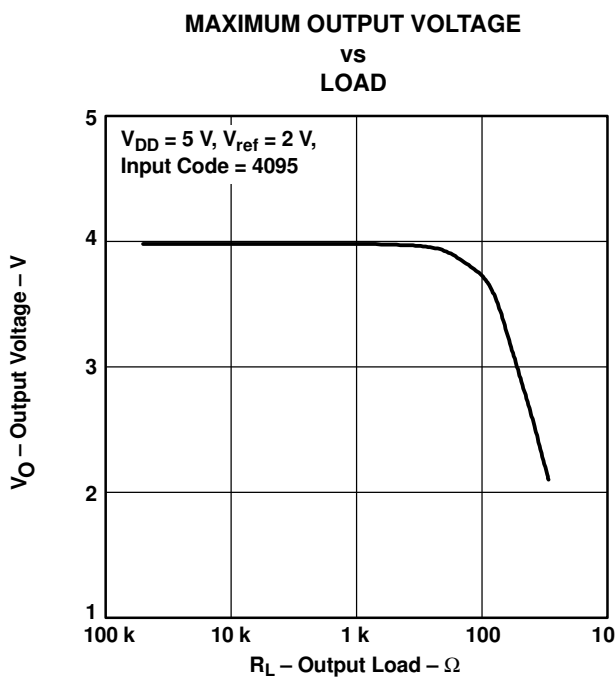


Figure 2.

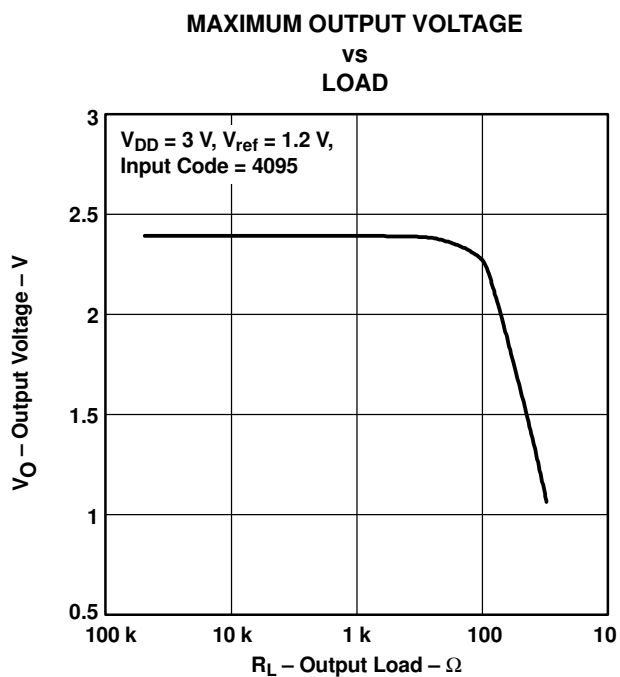


Figure 3.

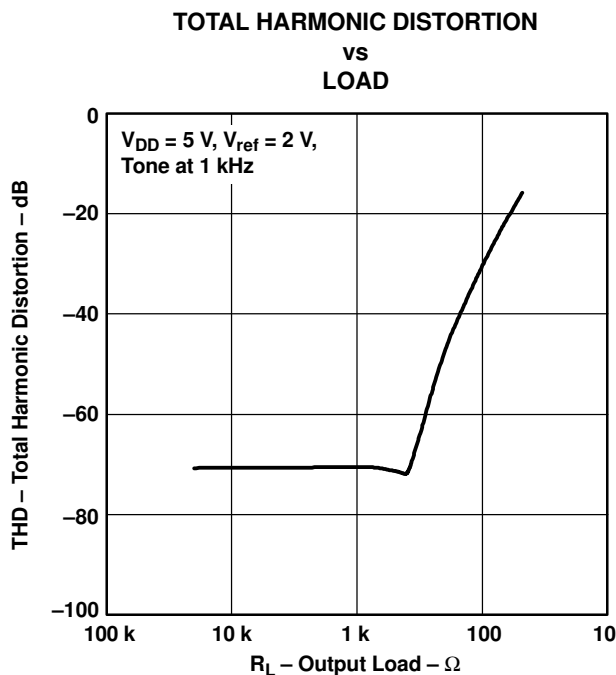


Figure 4.

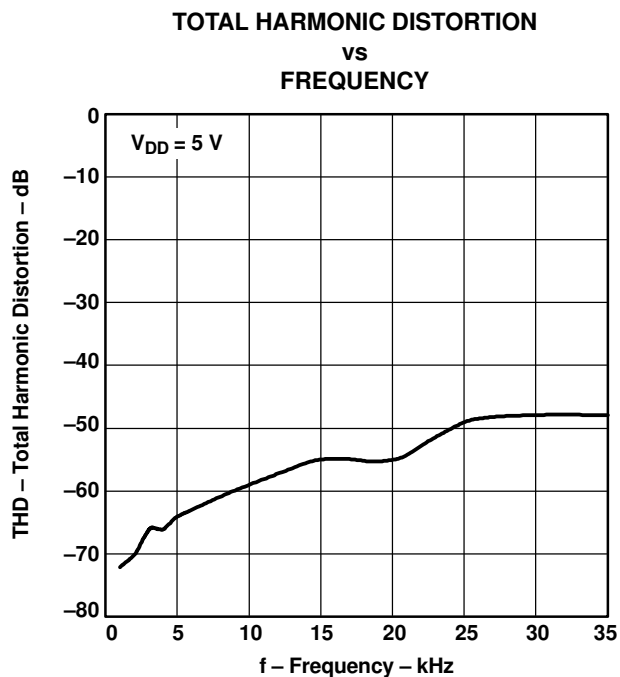


Figure 5.

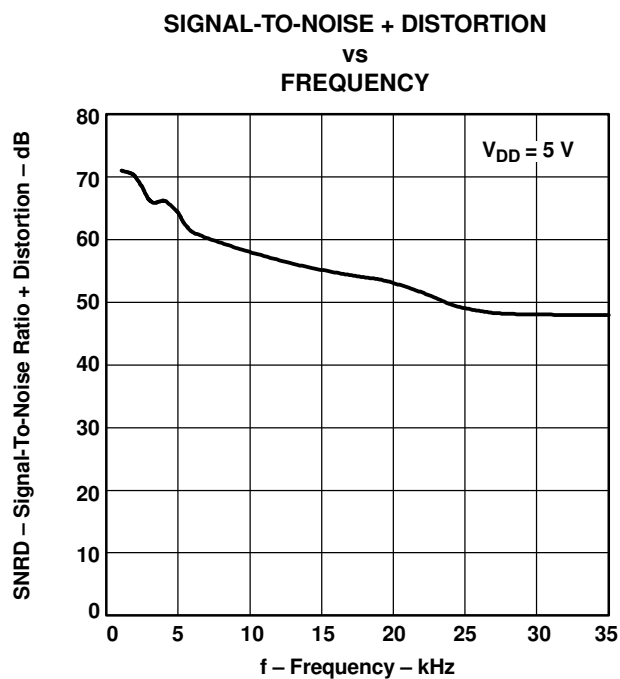
TYPICAL CHARACTERISTICS (continued)

Figure 6.

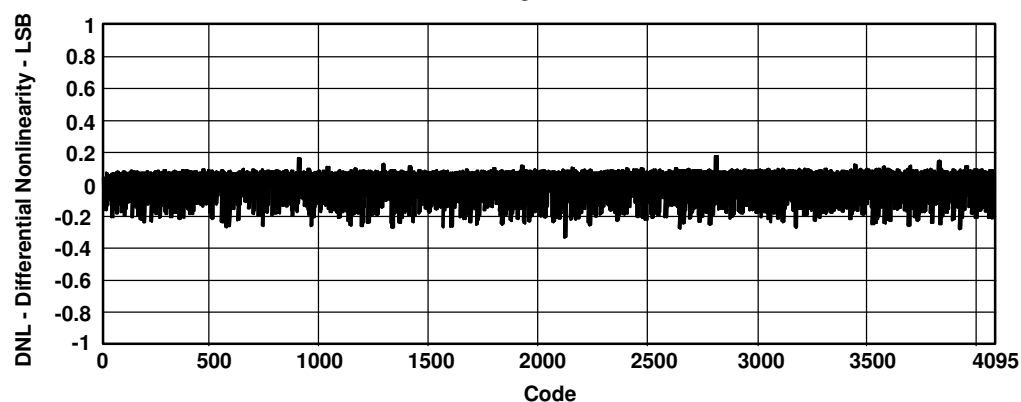


Figure 7. Differential Nonlinearity

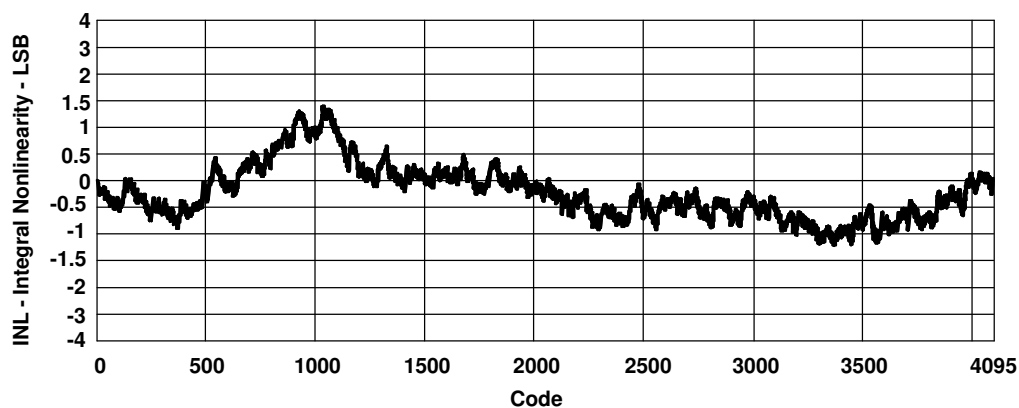


Figure 8. Integral Nonlinearity

TYPICAL CHARACTERISTICS (continued)

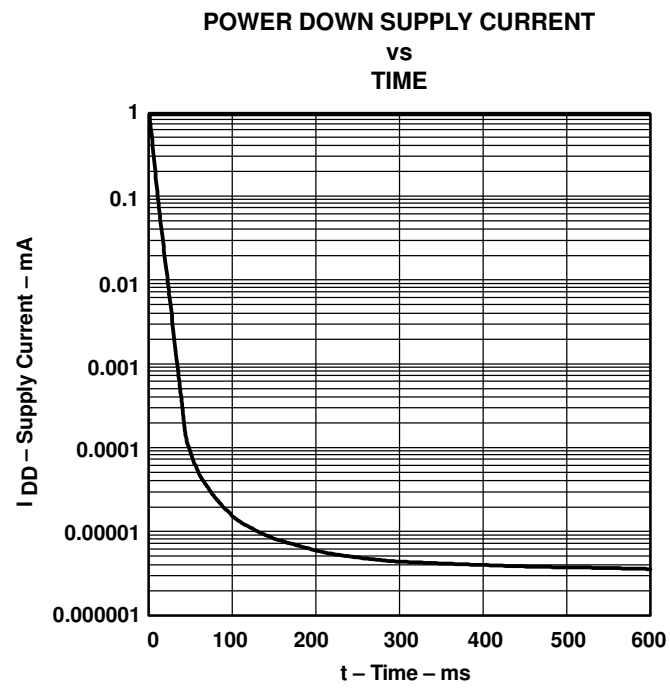


Figure 9.

APPLICATION INFORMATION

DEFINITIONS OF SPECIFICATIONS AND TERMINOLOGY

Integral Nonlinearity (INL)

The relative accuracy or integral nonlinearity (INL), sometimes referred to as linearity error, is the maximum deviation of the output from the line between zero and full scale excluding the effects of zero code and full-scale errors.

Differential Nonlinearity (DNL)

The differential nonlinearity (DNL), sometimes referred to as differential error, is the difference between the measured and ideal 1 LSB amplitude change of any two adjacent codes. Monotonic means the output voltage changes in the same direction (or remains constant) as a change in the digital input code.

Zero-Scale Error (E_{zs})

Zero-scale error is defined as the deviation of the output from 0 V at a digital input value of 0.

Gain Error (E_G)

Gain error is the error in slope of the DAC transfer function.

Signal-to-Noise Ratio + Distortion (S/N+D)

S/N+D is the ratio of the rms value of the output signal to the rms sum of all other spectral components below the Nyquist frequency, including harmonics but excluding dc. The value for S/N+D is expressed in decibels.

Spurious Free Dynamic Range (SFDR)

SFDR is the difference between the rms value of the output signal and the rms value of the largest spurious signal within a specified bandwidth. The value for SFDR is expressed in decibels.

Total Harmonic Distortion (THD)

THD is the ratio of the rms sum of the first six harmonic components to the rms value of the fundamental signal and is expressed in decibels.

APPLICATION INFORMATION (continued)

LINEARITY, OFFSET, AND GAIN ERROR USING SINGLE END SUPPLIES

When an amplifier is operated from a single supply, the voltage offset can still be either positive or negative. With a positive offset, the output voltage changes on the first code change. With a negative offset the output voltage may not change with the first code depending on the magnitude of the offset voltage.

The output amplifier attempts to drive the output to a negative voltage. However, because the most negative supply rail is ground, the output cannot drive below ground and clamps the output at 0 V.

The output voltage remains at zero until the input code value produces a sufficient positive output voltage to overcome the negative offset voltage, resulting in the transfer function shown in Figure 10.

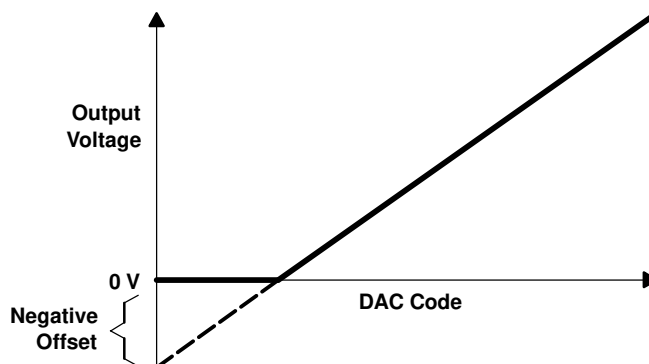


Figure 10. Effect of Negative Offset (Single Supply)

This offset error, not the linearity error, produces this breakpoint. The transfer function would have followed the dotted line if the output buffer could drive below the ground rail.

For a DAC, linearity is measured between zero input code (all inputs 0) and full scale code (all inputs 1) after offset and full scale are adjusted out or accounted for in some way. However, single supply operation does not allow for adjustment when the offset is negative due to the breakpoint in the transfer function. So the linearity is measured between full scale code and the lowest code that produces a positive output voltage.

GENERAL FUNCTION

The TLV5619 is a 12-bit, single supply DAC, based on a resistor string architecture. It consists of a parallel interface, a power down control logic, a resistor string, and a rail-to-rail output buffer. The output voltage (full scale determined by reference) is given by:

$$2 \text{ REF } \frac{\text{CODE}}{0x1000} \text{ [V]}$$

Where REF is the reference voltage and CODE is the digital input value, range 0x000 to 0xFFF. A power on reset initially puts the internal latches to a defined state (all bits zero).

APPLICATION INFORMATION (continued)

PARALLEL INTERFACE

The device latches data on the positive edge of $\overline{WE}$. It must be enabled with $\overline{CS}$ low. $\overline{LDAC}$ low updates the DAC with the value in the holding latch. $\overline{LDAC}$ is an asynchronous input and can be held low, if a separate update is not necessary. However, to control the DAC using the load feature, $\overline{LDAC}$ can be driven low after the positive $\overline{WE}$ edge.

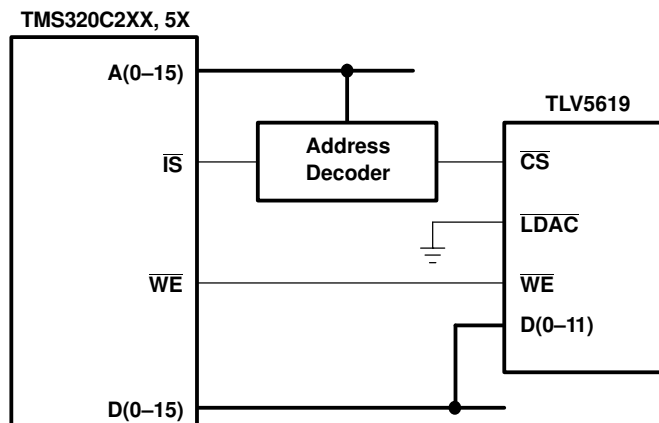


Figure 11. Proposed Interface Between TLV5619 and TMS320C2XX, 5X DSPs

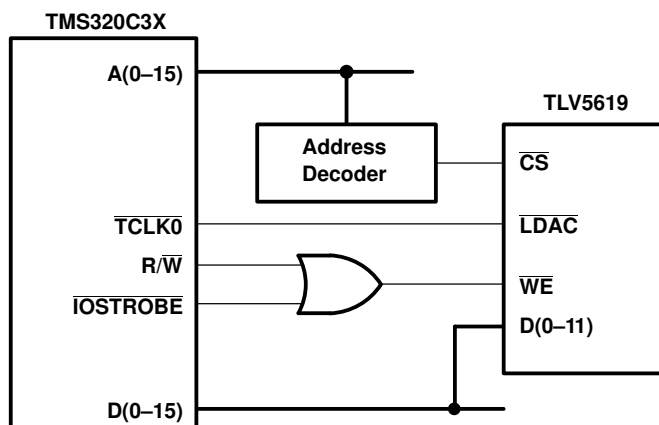


Figure 12. Proposed Interface Between TLV5619 and TMS320C3X DSPs

APPLICATION INFORMATION (continued)

TLV5619 INTERFACED TO TMS320C203 DSP

Hardware Interface

Figure 13 shows an example of the connection between the TLV5619 and the TMS320C203 DSP. The only other device that is needed in addition to the DSP and the DAC is the 74AC138 address decoding circuit. Using this configuration, the DAC address is 0x0084 within the I/O memory space of the TMS320C203.

$\overline{\text{LDAC}}$ is held low so that the output voltage is updated with the rising $\overline{\text{WE}}$ edge. The power down mode is deactivated permanently by pulling $\overline{\text{PD}}$ to V_{DD} .

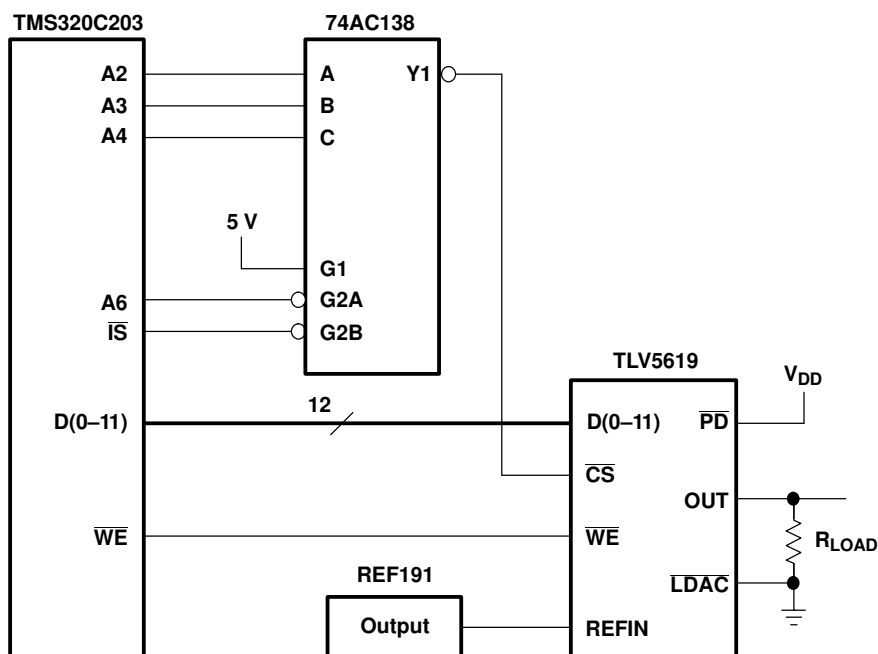


Figure 13. TLV5619 to TMS320C203 DSP Interface Connection

Software

No setup procedure is needed to access the TLV5619. The output voltage can be set using one command:

```
out data_addr, DAC_addr
```

Where `data_addr` points to the address location (in this example 0x0060) holding the new output voltage data and `DAC_addr` is the I/O space address of the TLV5619 (in this example 0x0084).

The following code shows, how to use the timer of the TMS320C203 as a time base to generate a voltage ramp with the TLV5619. A timer interrupt is generated every 205 μs . The corresponding interrupt service routine increments the output code (stored at 0x0060) for the DAC and writes the new code to the TLV5619. Only the 12 LSBs of the data in 0x0060 are used by the DAC, so that the resulting period of the saw waveform is:

- $t = 4096 \times 205 \text{ E-6 s} = 0.84 \text{ s}$

APPLICATION INFORMATION (continued)**SOFTWARE LISTING**

```

; File: ramp.asm
; Description: This program generates a ramp.

;----- I/O and memory mapped regs -----
                .include "regs.asm"
TLV5619         .equ    0084h
;----- vectors -----
                .ps      0h
                b        start
                b        INT1
                b        INT23
                b        TIM_ISR

*****
* Main Program
*****

                .ps      1000h
                .entry

start:
                ldp      #0      ; set data page to 0
; disable interrupts
                setc     INTM    ; disable maskable interrupts
                splk     #0ffffh, IFR
                splk     #0004h,  IMR

; set up the timer
                splk     #0000h,   60h
                splk     #0042h,   61h
                out      61h, PRD
                out      60h, TIM
                splk     #0c2fh,   62h
                out      62h, TCR

; enable interrupts
                clrc     INTM    ; enable maskable interrupts

; loop forever!
next           idle      ; wait for interrupt
                b        next
; all else fails stop here
done           b         done ; hang there

*****
* Interrupt Service Routines
*****

INT1:          ret        ; do nothing and return

INT23:         ret        ; do nothing and return

TIM_ISR:
                ; useful code
                add      #1h ; increment accumulator
                sac1     60h

```

APPLICATION INFORMATION (continued)

```
out      60h, TLV5619 ; write to DAC
clrc     intm; re-enable interrupts
ret      ; return from interrupt
.end
```

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package Pins	Package qty Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
TLV5619CDW	Active	Production	SOIC (DW) 20	25 TUBE	Yes	NIPDAU	Level-1-260C-UNLIM	0 to 70	TLV5619C
TLV5619CDW.A	Active	Production	SOIC (DW) 20	25 TUBE	Yes	NIPDAU	Level-1-260C-UNLIM	0 to 70	TLV5619C
TLV5619CDWR	Active	Production	SOIC (DW) 20	2000 LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	0 to 70	TLV5619C
TLV5619CDWR.A	Active	Production	SOIC (DW) 20	2000 LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	0 to 70	TLV5619C
TLV5619CPW	Active	Production	TSSOP (PW) 20	70 TUBE	Yes	NIPDAU	Level-1-260C-UNLIM	0 to 70	TV5619
TLV5619CPW.A	Active	Production	TSSOP (PW) 20	70 TUBE	Yes	NIPDAU	Level-1-260C-UNLIM	0 to 70	TV5619
TLV5619CPWR	Active	Production	TSSOP (PW) 20	2000 LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	0 to 70	TV5619
TLV5619CPWR.A	Active	Production	TSSOP (PW) 20	2000 LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	0 to 70	TV5619
TLV5619IDW	Active	Production	SOIC (DW) 20	25 TUBE	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	TLV5619I
TLV5619IDW.A	Active	Production	SOIC (DW) 20	25 TUBE	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	TLV5619I
TLV5619IDWR	Active	Production	SOIC (DW) 20	2000 LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	TLV5619I
TLV5619IDWR.A	Active	Production	SOIC (DW) 20	2000 LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	TLV5619I
TLV5619IPW	Active	Production	TSSOP (PW) 20	70 TUBE	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	TY5619
TLV5619IPW.A	Active	Production	TSSOP (PW) 20	70 TUBE	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	TY5619
TLV5619IPWR	Active	Production	TSSOP (PW) 20	2000 LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	TY5619
TLV5619IPWR.A	Active	Production	TSSOP (PW) 20	2000 LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	TY5619
TLV5619QDWG4	Active	Production	SOIC (DW) 20	25 TUBE	Yes	NIPDAU	Level-1-260C-UNLIM	-	TLV5619Q
TLV5619QDWG4.A	Active	Production	SOIC (DW) 20	25 TUBE	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	TLV5619Q

⁽¹⁾ **Status:** For more details on status, see our [product life cycle](#).

⁽²⁾ **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

⁽³⁾ **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

⁽⁴⁾ **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

(5) **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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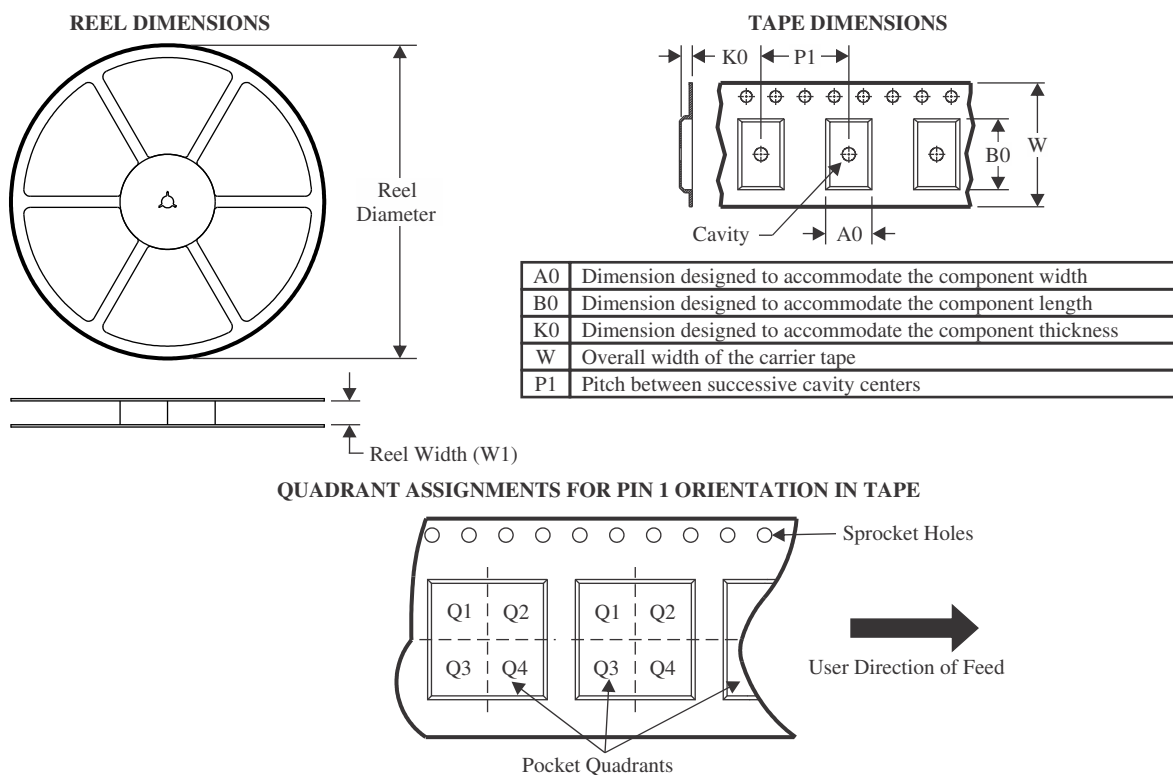
OTHER QUALIFIED VERSIONS OF TLV5619 :

- Enhanced Product : [TLV5619-EP](#)

NOTE: Qualified Version Definitions:

- Enhanced Product - Supports Defense, Aerospace and Medical Applications

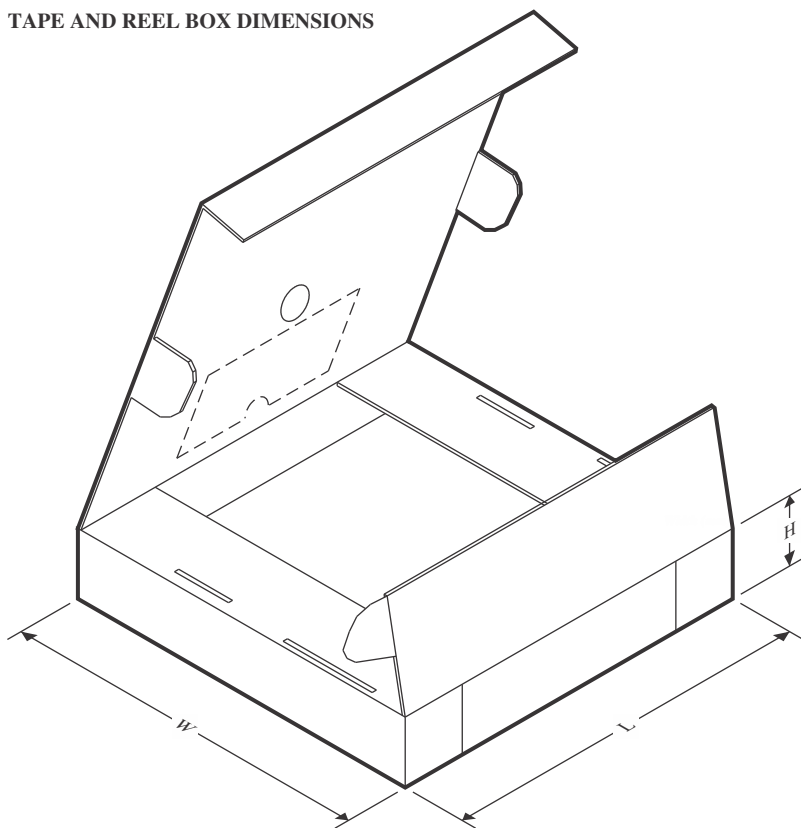
TAPE AND REEL INFORMATION



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TLV5619CDWR	SOIC	DW	20	2000	330.0	24.4	10.8	13.3	2.7	12.0	24.0	Q1
TLV5619CPWR	TSSOP	PW	20	2000	330.0	16.4	6.95	7.1	1.6	8.0	16.0	Q1
TLV5619IDWR	SOIC	DW	20	2000	330.0	24.4	10.8	13.3	2.7	12.0	24.0	Q1
TLV5619IPWR	TSSOP	PW	20	2000	330.0	16.4	6.95	7.1	1.6	8.0	16.0	Q1

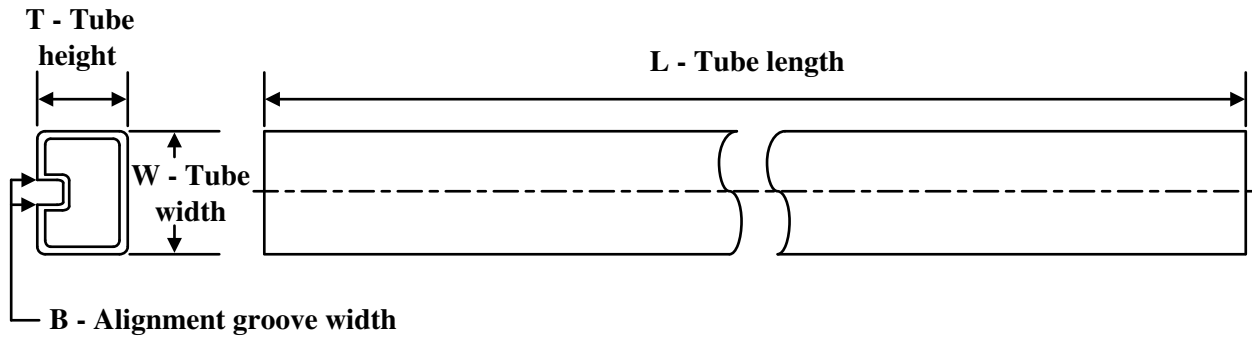
TAPE AND REEL BOX DIMENSIONS



*All dimensions are nominal

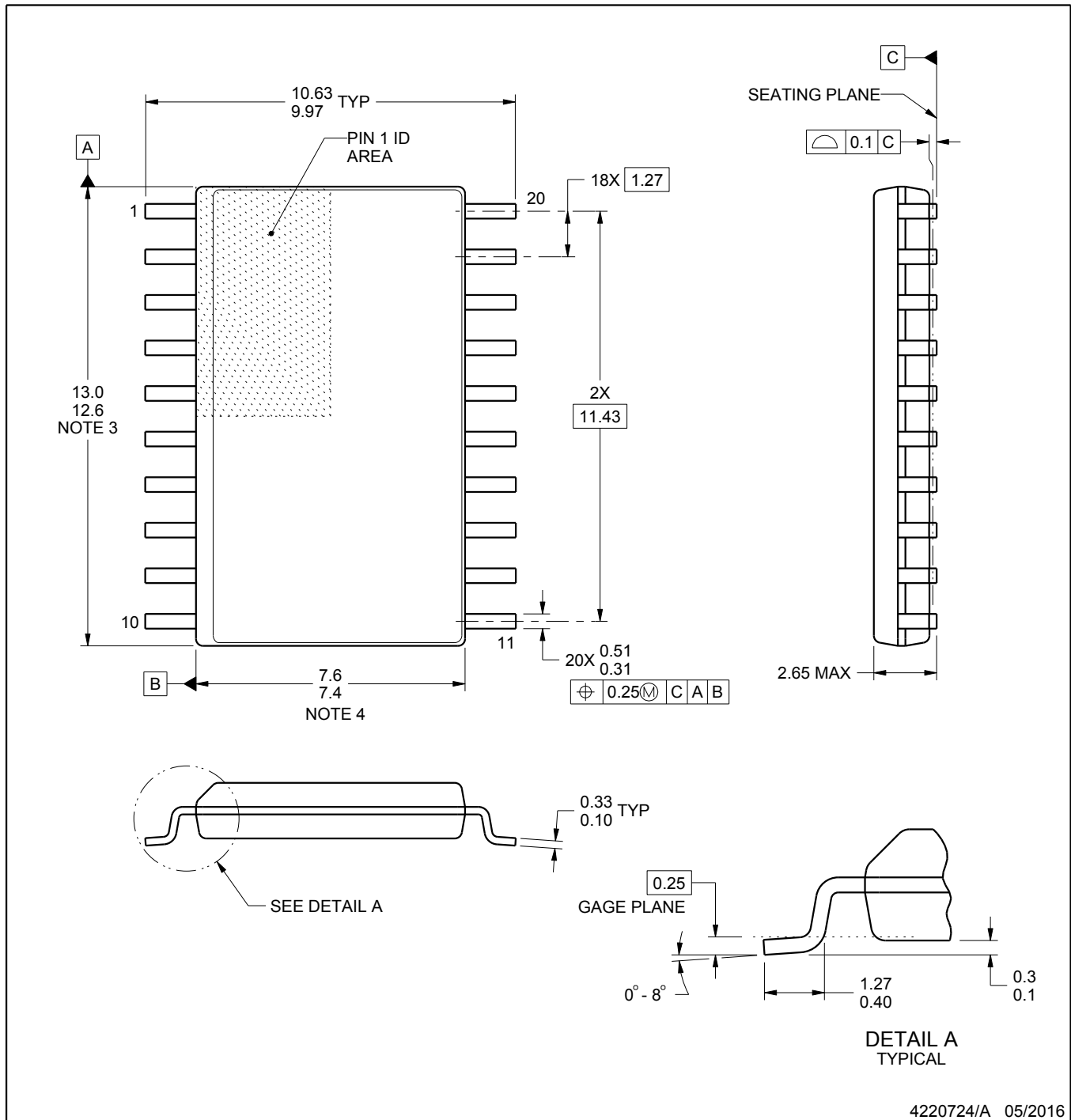
Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TLV5619CDWR	SOIC	DW	20	2000	350.0	350.0	43.0
TLV5619CPWR	TSSOP	PW	20	2000	350.0	350.0	43.0
TLV5619IDWR	SOIC	DW	20	2000	350.0	350.0	43.0
TLV5619IPWR	TSSOP	PW	20	2000	350.0	350.0	43.0

TUBE



*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	L (mm)	W (mm)	T (μm)	B (mm)
TLV5619CDW	DW	SOIC	20	25	506.98	12.7	4826	6.6
TLV5619CDW.A	DW	SOIC	20	25	506.98	12.7	4826	6.6
TLV5619CPW	PW	TSSOP	20	70	530	10.2	3600	3.5
TLV5619CPW.A	PW	TSSOP	20	70	530	10.2	3600	3.5
TLV5619IDW	DW	SOIC	20	25	506.98	12.7	4826	6.6
TLV5619IDW.A	DW	SOIC	20	25	506.98	12.7	4826	6.6
TLV5619IPW	PW	TSSOP	20	70	530	10.2	3600	3.5
TLV5619IPW.A	PW	TSSOP	20	70	530	10.2	3600	3.5
TLV5619QDWG4	DW	SOIC	20	25	506.98	12.7	4826	6.6
TLV5619QDWG4.A	DW	SOIC	20	25	506.98	12.7	4826	6.6



4220724/A 05/2016

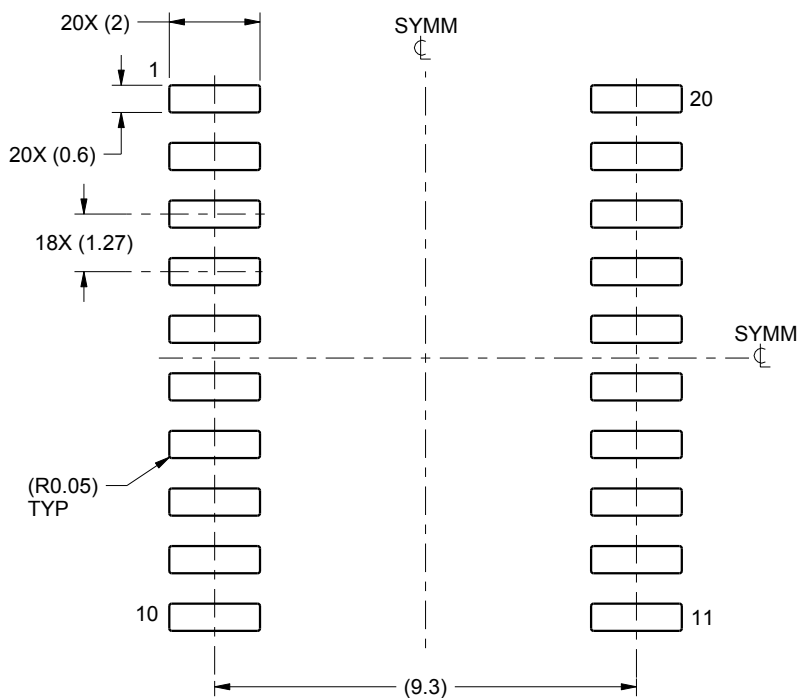
NOTES:

1. All linear dimensions are in millimeters. Dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 mm per side.
4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.43 mm per side.
5. Reference JEDEC registration MS-013.

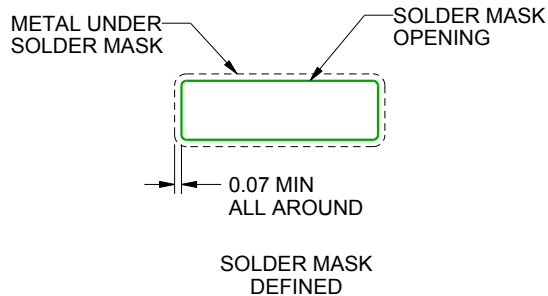
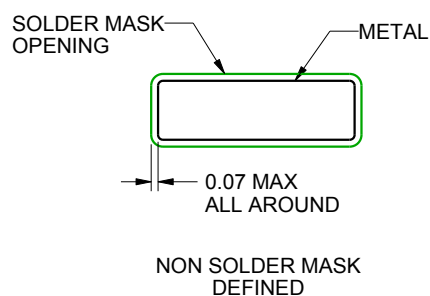
DW0020A

SOIC - 2.65 mm max height

SOIC



LAND PATTERN EXAMPLE
SCALE:6X



SOLDER MASK DETAILS

4220724/A 05/2016

NOTES: (continued)

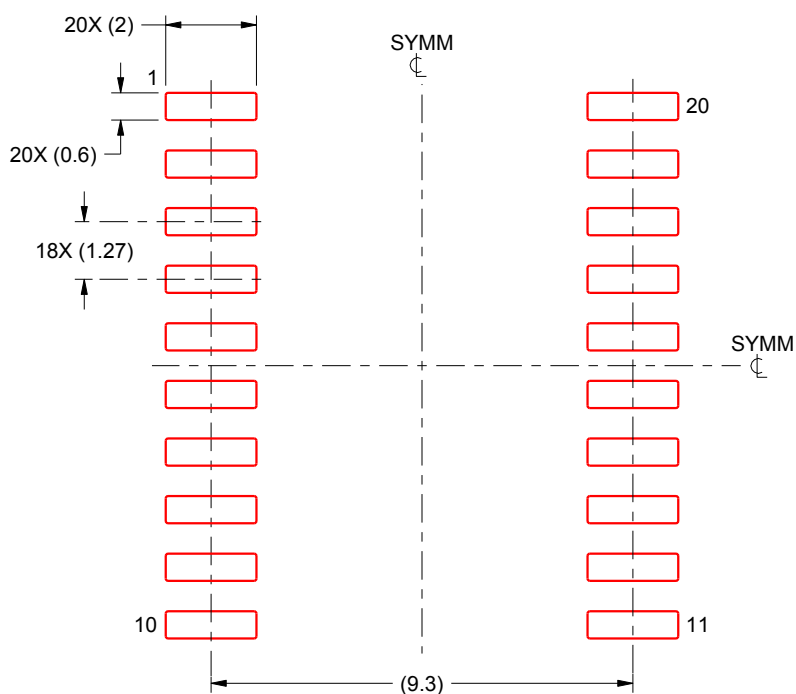
6. Publication IPC-7351 may have alternate designs.
7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

EXAMPLE STENCIL DESIGN

DW0020A

SOIC - 2.65 mm max height

SOIC



SOLDER PASTE EXAMPLE
BASED ON 0.125 mm THICK STENCIL
SCALE:6X

4220724/A 05/2016

NOTES: (continued)

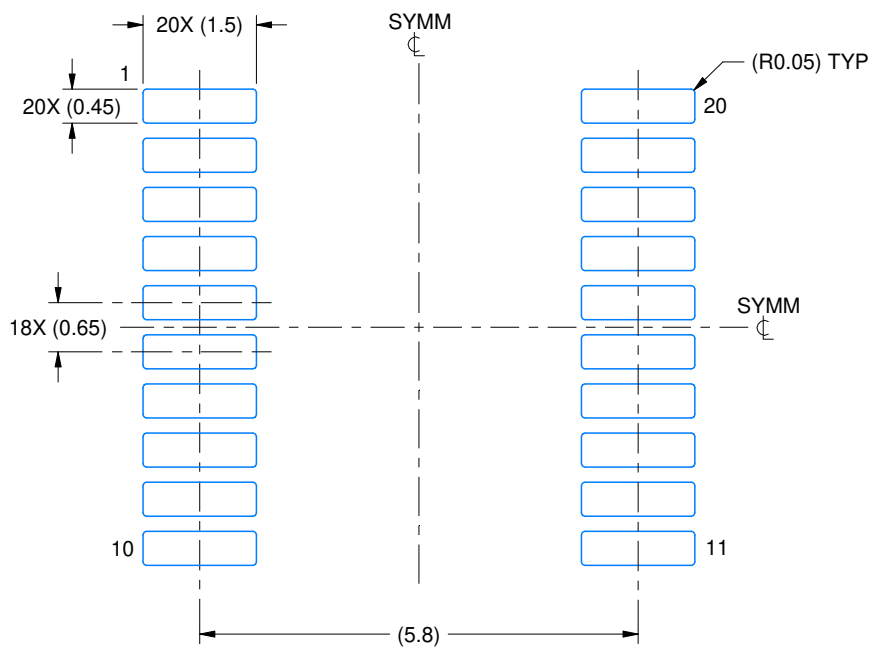
8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

EXAMPLE BOARD LAYOUT

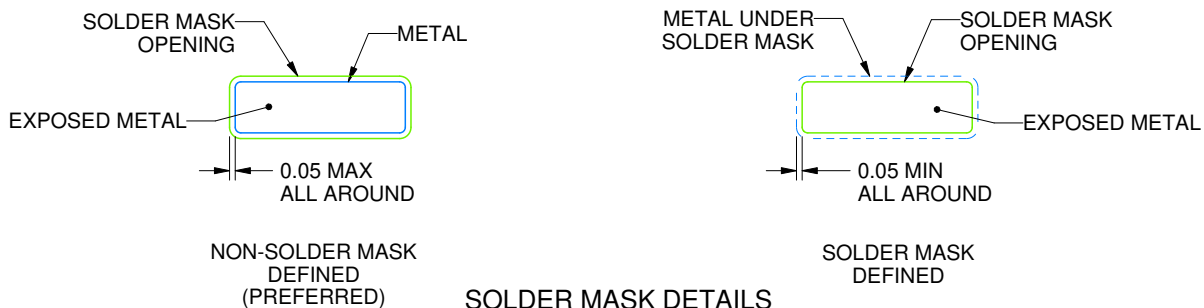
PW0020A

TSSOP - 1.2 mm max height

SMALL OUTLINE PACKAGE



LAND PATTERN EXAMPLE
EXPOSED METAL SHOWN
SCALE: 10X



4220206/A 02/2017

NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

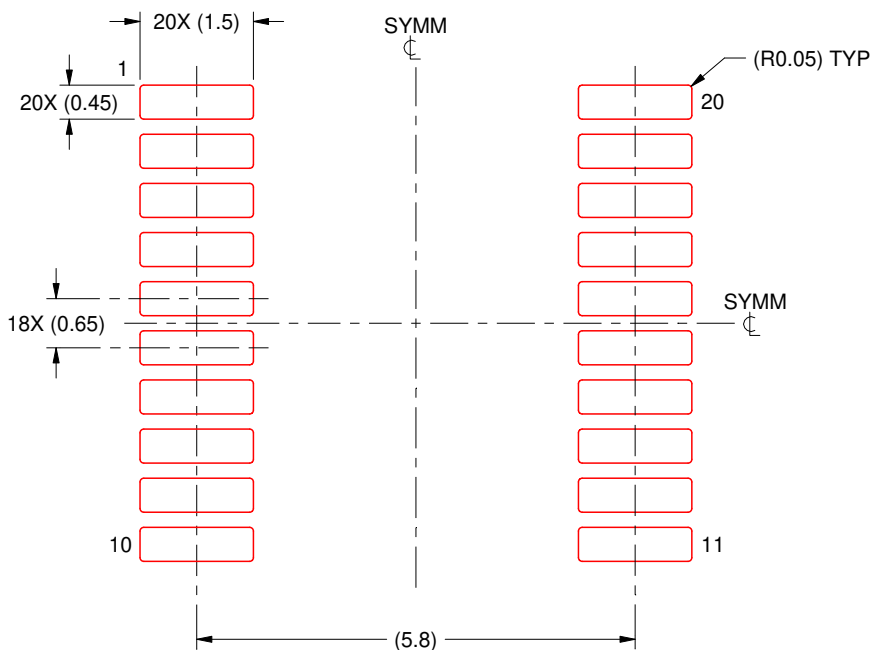
7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

EXAMPLE STENCIL DESIGN

PW0020A

TSSOP - 1.2 mm max height

SMALL OUTLINE PACKAGE



SOLDER PASTE EXAMPLE
BASED ON 0.125 mm THICK STENCIL
SCALE: 10X

4220206/A 02/2017

NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

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Last updated 10/2025